



A Common Fixed Point Theorem in M-Fuzzy Metric Spaces for Integral type Inequality

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ABSTRACT: In this paper, we mainly give a common fixed point theorem for three pairs of weakly compatible maps in M-fuzzy metric spaces for integral type inequality by introducing Common property (E) for two pairs of mappings.

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I. INTRODUCTION

The concept of sets was introduced by Zadeh [9] in 1965, I. Kramosil and J. Michalek [7] introduced the concept of fuzzy topological spaces induced by fuzzy metric which have very important applications in quantum particle physics. Consequently in due course of time many researchers have defined a fuzzy metric space in different ways. Researchers like A. George and P. Veeramani [2], M. Grabiec [10], P.V. Subrahmanyam [11], R. Vasuki [12] used this concept to generalize some metric fixed point results. Recently, Sedghi and Shobe [17] introduced M-fuzzy metric space which is based on D*-metric concept. Dhage [5] introduced the notion of generalized metric or D-metric spaces by S.V.R. Naidu, K.P.R. Rao and N.Srinivasa Rao [14], [15], [16] and proved several fixed point theorems in it. Also proved a Common fixed point theorem for three pairs of maps in M-Fuzzy metric spaces by K. P. R. Rao, G. Ravi Babu and V.C.C. Raju [8].

II. PRELIMINARIES

Definition 2.1 [1]: Let (X, d) be a complete metric space, $c \in (0, 1)$ and $f: X \rightarrow X$ be a mapping such that for each $x, y \in X$,

$$\int_0^{d(fx, fy)} \varphi(t) dt \leq c \int_0^{d(x, y)} \varphi(t) dt$$

where $\varphi: [0, +\infty) \rightarrow [0, +\infty)$ is a Lebesgue integrable mapping which is summable on each compact subset of $[0, +\infty)$, non negative, and such that for each $\varepsilon > 0$, $\int_0^\varepsilon \varphi(t) dt > 0$, then f has a unique fixed point $a \in X$ such that for each $x \in X$, $\lim_{n \rightarrow \infty} f^n x = a$.

B.E. Rhoades [3], extending the result of Branciari by replacing the above condition by the following

$$\int_0^{d(fx, fy)} \varphi(t) dt \leq c \int_0^{\max\{d(x, y), d(x, fx), d(y, fy), \frac{d(x, fy) + d(y, fx)}{2}\}} \varphi(t) dt.$$

Definition 2.2 [4]: A binary operation $*$: $[0, 1] \times [0, 1] \rightarrow [0, 1]$ is a continuous t-norm if it satisfies the following conditions:

- (1) $*$ is associative and commutative,
- (2) $*$ is continuous,
- (3) $a * 1 = a$ for all $a \in [0, 1]$,

(4) $a * b \leq c * d$ whenever $a \leq c$ and $b \leq d$ for all $a, b, c, d \in [0, 1]$,

Two typical examples of continuous t-norm are $a * b = ab$ and $a * b = \min(a, b)$.

Definition 2.3 [17]: A 3-tuple $(X, M, *)$ is called a M-fuzzy metric space if X is an arbitrary (Non-empty) set, $*$ is a continuous t-norm and M is a fuzzy set on $X^3 \times (0, \infty)$ satisfying the following conditions: for all $x, y, z, a \in X$ and $t, s > 0$,

- (1) $M(x, y, t) > 0$.
- (2) $M(x, y, z, t) = 1$ if and only if $x = y = z$,
- (3) $M(x, y, z, t) = M(p\{x, y, z\}, t)$, (symmetry) where p is a permutation function
- (4) $M(x, y, a, t) * M(a, z, z, s) \leq M(x, y, z, t + s)$.
- (5) $M(x, y, z, \cdot) : (0, \infty) \rightarrow [0, 1]$ is continuous.

Remark 2.1 [17]. Let $(X, M, *)$ be a M-fuzzy metric space. Then for every $t > 0$ and for every $x, y \in X$, we have $M(x, x, y, t) = M(x, y, y, t)$.

Definition 2.4 [17]. Let $(X, M, *)$ be a M-fuzzy metric space. For $t > 0$, the open ball

$B_M(x, r, t)$ with center $x \in X$ and radius $0 < r < 1$ is defined by

$B_M(x, r, t) = \{y \in X : M(x, y, y, t) > 1 - r\}$. A subset A of X is called open set if for each $x \in A$ there exist $t > 0$ and $0 < r < 1$ such that $B_M(x, r, t) \subseteq A$.

Definition 2.5 [17]. A sequence $\{x_n\}$ in X converges to x if and only if $M(x, x, x_n, t) \rightarrow 1$ as $n \rightarrow \infty$, for each $t > 0$. It is called a Cauchy sequence if for each $0 < \epsilon < 1$ and $t > 0$, there exists $n_0 \in \mathbb{N}$ such that $M(x_n, x_n, x_m, t) > 1 - \epsilon$ for each $n, m \geq n_0$. The M-fuzzy metric space $(X, M, *)$ is said to be complete if every Cauchy sequence is convergent.

Lemma 2.1[17]. Let $(X, M, *)$ be a M-fuzzy metric space. Then $M(x, y, z, t)$ is non decreasing with respect to t , for all x, y, z in X .

Lemma 2.2 [17]. Let $(X, M, *)$ be a M-fuzzy metric space. Then M is Continuous function on $X^3 \times (0, \infty)$.

Definition 2.6[17]. Let f and g be two self maps of $(X, M, *)$. Then f and g are said to satisfy property (E), if there exists a sequence $\{x_n\}$ in X such that $M(fx_n, u, u, t) \rightarrow 1$ & $M(gx_n, u, u, t) \rightarrow 1$ as $n \rightarrow \infty$ for some u in X and for every $t > 0$.

Liu et.al [18] defined common property (E) for two pairs of maps in a metric space. In 1998, Jungck and Rhoades [6] introduced the concept of weakly compatibility of pair of self mappings in a metric space.

Definition 2.7[17]. Let f and g be two self maps of $(X, M, *)$. Then f and g are said to be weakly compatible if there exists u in X with $fu = gu$ implies $fgu = gfu$.

Definition 2.8[8]. Let P, Q, f and g be self mappings on M-fuzzy metric space $(X, M, *)$. We say that the pairs (P, f) and (Q, g) satisfy common property (E) if there exist sequences $\{x_n\}$ and $\{y_n\}$ in X such that $M(Px_n, u, u, t) \rightarrow 1$, $M(fx_n, u, u, t) \rightarrow 1$, $M(Qy_n, u, u, t) \rightarrow 1$ and $M(gy_n, u, u, t) \rightarrow 1$ as $n \rightarrow \infty$ for some u in X and for every $t > 0$.

Example 2.1[8]. Let $X = \mathbb{R}$ & $M(x, y, z, t) = \frac{t}{t + |x-y| + |y-z| + |x-z|}$ for all $t > 0$ & $x, y, z \in X$. Let $P, Q, f, g : X \rightarrow X$ be defined by $Px = 2x + 1, fx = x + 2, Qx = 2x + 5$ and $gx = 2 - x$. Consider the sequences $\{x_n\} = \{1 + \frac{1}{n}\}$ and $\{y_n\} = \{-1 + \frac{1}{n}\}$.

Then $M(Px_n, 3, 3, t) \rightarrow 1, M(fx_n, 3, 3, t) \rightarrow 1, M(Qx_n, 3, 3, t) \rightarrow 1$ and $M(gx_n, 3, 3, t) \rightarrow 1$ as $n \rightarrow \infty$ for every $t > 0$. Thus the pairs (P, f) and (Q, g) satisfy common property (E).

3. Main Results

Theorem 3.1 Let P, Q, R, f, g and h be self mappings of a M-fuzzy metric space $(X, M, *)$ satisfying

(3.1.1) $P(X) \subseteq g(X), Q(X) \subseteq h(X), R(X) \subseteq f(X)$ and $f(X)$ or $g(X)$ or $h(X)$ is a closed subspace of X ,

(3.1.2) the pairs $(P, f), (Q, g)$ and (R, h) are weakly compatible,

(3.1.3) any two pairs from $(P, f), (Q, g)$ and (R, h) satisfy common property (E) and

(3.1.4)

$$\int_0^{M(Px, Qy, Rz, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \varphi \left(\min \left(\frac{M(fx, gy, hz, t), M(fx, Px, Qy, t)}{M(gy, Qy, Rz, t), M(hz, Rz, Px, t)} \right) \right) \right\}} \left(\frac{M(fx, Qy, hz, t) \cdot M(Px, Qy, hz, t)}{M(fx, gy, hz, t) \cdot M(Px, gy, hz, t)} \right) \xi(t) dt$$

$x, y, z \in X, \forall t > 0$, and $\varphi, \delta, \phi : (0, \infty) \rightarrow (0, \infty)$ is such that $\phi(t) < t, \varphi(t) < t, \delta(t) < t$.

Then P, Q, R, f, g and h have a unique common fixed point in X .

Proof.

Suppose the pairs (P, f) and (Q, g) satisfy common property (E). Then there exist sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$\lim_n Px_n = \lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} Qy_n = \lim_{n \rightarrow \infty} gy_n = \alpha$$

For some $\alpha \in X$.

Since $Q(X) \subseteq h(X)$, there exists a sequence $\{z_n\}$ in X such that $Qy_n = hz_n$, $n = 1, 2, \dots$. Hence $\lim_n hz_n = \alpha$. Let $\lim_{n \rightarrow \infty} Rz_n = \gamma$.

Now from (3.1.4), we have

$$\int_0^{M(Px_n, Qy_n, Rz_n, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(fx_n, gy_n, hz_n, t), M(fx_n, Px_n, Qy_n, t)}{M(gy_n, Qy_n, Rz_n, t), M(hz_n, Rz_n, Px_n, t)} \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(fx_n, Qy_n, hz_n, t)}{M(fx_n, gy_n, hz_n, t)}, \frac{M(Px_n, Qy_n, hz_n, t)}{M(Px_n, gy_n, hz_n, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

Letting $n \rightarrow \infty$, we get

$$\int_0^{M(\alpha, \alpha, \gamma, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(\alpha, \alpha, \alpha, t), M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, \gamma, t), M(\alpha, \gamma, \alpha, t)} \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, \alpha, t)}, \frac{M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, \alpha, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

$$\int_0^{M(\alpha, \alpha, \gamma, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi(M(\alpha, \alpha, \gamma, t)) \\ + \\ \delta(1) \end{array} \right\}} \xi(t) dt \geq \int_0^{M(\alpha, \alpha, \gamma, t)} \xi(t) dt$$

$$i.e \int_0^{M(\alpha, \alpha, \gamma, \phi(t))} \xi(t) dt \geq \int_0^{M(\alpha, \alpha, \gamma, t)} \xi(t) dt$$

So that $\gamma = \alpha$.

Thus $\lim_{n \rightarrow \infty} Rz_n = \alpha$

Suppose $f(X)$ is a closed subspace of X . Then $\alpha = fu$ for some $u \in X$. Now in (3.1.4)

$$\int_0^{M(Pu, Qy_n, Rz_n, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(fu, gy_n, hz_n, t), M(fu, Pu, Qy_n, t)}{M(gy_n, Qy_n, Rz_n, t), M(hz_n, Rz_n, Pu, t)} \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(fu, Qy_n, hz_n, t)}{M(fu, gy_n, hz_n, t)}, \frac{M(Pu, Qy_n, hz_n, t)}{M(Pu, gy_n, hz_n, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

Letting $n \rightarrow \infty$, we get

$$\int_0^{M(Pu, \alpha, \alpha, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(\alpha, \alpha, \alpha, t), M(\alpha, Pu, \alpha, t)}{M(\alpha, \alpha, \alpha, t), M(\alpha, \alpha, Pu, t)} \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, \alpha, t)}, \frac{M(Pu, \alpha, \alpha, t)}{M(Pu, \alpha, \alpha, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

$$\int_0^{M(Pu,\alpha,\alpha,\emptyset(t))} \xi(t)dt \geq \int_0^{\left\{ \begin{matrix} \varphi(M(Pu,\alpha,\alpha,t)) \\ + \\ \delta(1) \end{matrix} \right\}} \xi(t)dt \geq \int_0^{\{M(Pu,\alpha,\alpha,t)\}} \xi(t)dt$$

$$i. e \int_0^{M(Pu,\alpha,\alpha,\emptyset(t))} \xi(t)dt \geq \int_0^{\{M(Pu,\alpha,\alpha,t)\}} \xi(t)dt$$

So that $Pu = \alpha$.
 Since the pair (P, f) is weakly compatible and $Pu = fu = \alpha$, we have $P\alpha = f\alpha$.
 Since $P(X) \subseteq h(X)$, there exists $v \in X$ such that $\alpha = Pu = gv$. Now we have (3.1.4)

$$\int_0^{M(Pu,Qv,Rz_n,\emptyset(t))} \xi(t)dt \geq \int_0^{\left\{ \begin{matrix} \varphi \left(\min \left(\begin{matrix} M(fu,gv,hz_n,t), M(fu,Pu,Qv,t), \\ M(gv,Qv,Rz_n,t), M(hz_n,Rz_n,Pu,t), \\ M(fu,gv,Rz_n,t), M(Pu,gv,hz_n,t) \end{matrix} \right) \right) \\ + \\ \delta \left(\min \left(\begin{matrix} M(fu,Qv,hz_n,t) \\ M(Pu,Qv,hz_n,t) \end{matrix} \right) \right) \end{matrix} \right\}} \xi(t)dt$$

Letting $n \rightarrow \infty$, we get

$$\int_0^{M(\alpha,Qv,\alpha,\emptyset(t))} \xi(t)dt \geq \int_0^{\left\{ \begin{matrix} \varphi \left(\min \left(\begin{matrix} M(\alpha,\alpha,\alpha,t), M(\alpha,\alpha,Qv,t), \\ M(\alpha,Qv,\alpha,t), M(\alpha,\alpha,\alpha,t), \\ M(\alpha,\alpha,\alpha,t), M(\alpha,\alpha,\alpha,t) \end{matrix} \right) \right) \\ + \\ \delta \left(\min \left(\begin{matrix} M(\alpha,Qv,\alpha,t) \\ M(\alpha,\alpha,\alpha,t) \end{matrix} \right) \right) \end{matrix} \right\}} \xi(t)dt$$

$$\int_0^{M(\alpha,Qv,\alpha,\emptyset(t))} \xi(t)dt \geq \int_0^{\left\{ \begin{matrix} \varphi(M(\alpha,Qv,\alpha,t)) \\ + \\ \delta(M(\alpha,Qv,\alpha,t)) \end{matrix} \right\}} \xi(t)dt \geq \int_0^{\{M(\alpha,Qv,\alpha,t)\}} \xi(t)dt$$

$$i. e \int_0^{M(\alpha,Qv,\alpha,\emptyset(t))} \xi(t)dt \geq \int_0^{\{M(\alpha,Qv,\alpha,t)\}} \xi(t)dt$$

So that $Qv = \alpha$.
 Since the pair (Q, g) is weakly compatible and $Qv = gv = \alpha$, we have $Q\alpha = g\alpha$.
 Since $Q(X) \subseteq h(X)$, there exists $w \in X$ such that $\alpha = Qv = hw$. Now we have (3.1.4)

$$\int_0^{M(Pu,Qv,Rw,\emptyset(t))} \xi(t)dt \geq \int_0^{\left\{ \begin{matrix} \varphi \left(\min \left(\begin{matrix} M(fu,gv,hw,t), M(fu,Pu,Qv,t), \\ M(gv,Qv,Rw,t), M(hw,Rw,Pu,t), \\ M(fu,gv,Rw,t), M(Pu,gv,hw,t) \end{matrix} \right) \right) \\ + \\ \delta \left(\min \left(\begin{matrix} M(fu,Qv,hw,t) \\ M(Pu,Qv,hw,t) \end{matrix} \right) \right) \end{matrix} \right\}} \xi(t)dt$$

$$\int_0^{M(\alpha, \alpha, R_w, \emptyset(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(\alpha, \alpha, \alpha, t), M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, R_w, t), M(\alpha, R_w, \alpha, t)}, \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, \alpha, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

$$\int_0^{M(\alpha, \alpha, R_w, \emptyset(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi(M(\alpha, \alpha, R_w, t)) \\ + \\ \delta(1) \end{array} \right\}} \xi(t) dt \geq \int_0^{\{M(\alpha, \alpha, R_w, t)\}} \xi(t) dt$$

$$i. e \int_0^{M(\alpha, \alpha, R_w, \emptyset(t))} \xi(t) dt \geq \int_0^{\{M(\alpha, \alpha, R_w, t)\}} \xi(t) dt$$

So that $R_w = \alpha$.

Since the pair (R, h) is weakly compatible, we have $R\alpha = h$. From (3.1.4) we have

$$\int_0^{M(P\alpha, \alpha, \alpha, \emptyset(t))} \xi(t) dt \geq \int_0^{M(P\alpha, Qv, R_w, \emptyset(t))} \xi(t) dt$$

$$\int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(f\alpha, g\nu, h\nu, t), M(f\alpha, P\alpha, Qv, t)}{M(g\nu, Qv, R_w, t), M(h\nu, R_w, P\alpha, t)}, \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(f\alpha, Qv, h\nu, t)}{M(f\alpha, g\nu, h\nu, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

$$\int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(P\alpha, \alpha, \alpha, t), M(P\alpha, P\alpha, \alpha, t)}{M(\alpha, \alpha, \alpha, t), M(\alpha, \alpha, P\alpha, t)}, \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(P\alpha, \alpha, \alpha, t)}{M(P\alpha, \alpha, \alpha, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

$$\int_0^{M(P\alpha, \alpha, \alpha, \emptyset(t))} \xi(t) dt \geq \int_0^{\left\{ \begin{array}{l} \varphi(M(P\alpha, \alpha, \alpha, t)) \\ + \\ \delta(1) \end{array} \right\}} \xi(t) dt \geq \int_0^{\{M(P\alpha, \alpha, \alpha, t)\}} \xi(t) dt$$

$$i. e \int_0^{M(P\alpha, \alpha, \alpha, \emptyset(t))} \xi(t) dt \geq \int_0^{\{M(P\alpha, \alpha, \alpha, t)\}} \xi(t) dt$$

From remark (2.1), So that $P\alpha = \alpha$ and $P\alpha = \alpha = f\alpha$. Now we have

$$\int_0^{M(\alpha, Q\alpha, \alpha, \emptyset(t))} \xi(t) dt \geq \int_0^{M(P\alpha, Q\alpha, R_w, \emptyset(t))} \xi(t) dt$$

$$\int_0^{\left\{ \begin{array}{l} \varphi \left(\min \left(\frac{M(f\alpha, g\alpha, h\nu, t), M(f\alpha, P\alpha, Q\alpha, t)}{M(g\alpha, Q\alpha, R_w, t), M(h\nu, R_w, P\alpha, t)}, \right) \right) \\ + \\ \delta \left(\min \left(\frac{M(f\alpha, Q\alpha, h\nu, t)}{M(f\alpha, g\alpha, h\nu, t)} \right) \right) \end{array} \right\}} \xi(t) dt$$

$$\int_0^{\left\{ \varphi \left(\min \left(\frac{M(\alpha, Q\alpha, \alpha, t), M(\alpha, \alpha, Q\alpha, t)}{M(Q\alpha, Q\alpha, \alpha, t), M(\alpha, \alpha, \alpha, t)}, \frac{M(\alpha, Q\alpha, \alpha, t), M(\alpha, Q\alpha, \alpha, t)}{M(\alpha, Q\alpha, \alpha, t), M(\alpha, Q\alpha, \alpha, t)} \right) \right) \right\}} \delta \left(\min \left(\frac{M(\alpha, Q\alpha, \alpha, t)}{M(\alpha, Q\alpha, \alpha, t)}, \frac{M(\alpha, Q\alpha, \alpha, t)}{M(\alpha, Q\alpha, \alpha, t)} \right) \right) \xi(t) dt$$

$$\int_0^{M(\alpha, Q\alpha, \alpha, \vartheta(t))} \xi(t) dt \geq \int_0^{\left\{ \varphi(M(\alpha, Q\alpha, \alpha, t)) \right\}} \delta(1) \xi(t) dt \geq \int_0^{\{M(\alpha, Q\alpha, \alpha, t)\}} \xi(t) dt$$

$$i. e \int_0^{M(\alpha, Q\alpha, \alpha, \vartheta(t))} \xi(t) dt \geq \int_0^{\{M(\alpha, Q\alpha, \alpha, t)\}} \xi(t) dt$$

From remark (2.1), So that $Q\alpha = \alpha$ and hence $Q\alpha = \alpha = g\alpha$. Now we have

$$\int_0^{M(\alpha, \alpha, R\alpha, \vartheta(t))} \xi(t) dt \geq \int_0^{M(P\alpha, Q\alpha, R\alpha, \vartheta(t))} \xi(t) dt$$

$$\int_0^{\left\{ \varphi \left(\min \left(\frac{M(f\alpha, g\alpha, h\alpha, t), M(f\alpha, P\alpha, Q\alpha, t)}{M(g\alpha, Q\alpha, R\alpha, t), M(h\alpha, R\alpha, P\alpha, t)}, \frac{M(f\alpha, g\alpha, R\alpha, t), M(P\alpha, g\alpha, h\alpha, t)}{M(f\alpha, g\alpha, R\alpha, t), M(P\alpha, g\alpha, h\alpha, t)} \right) \right) \right\}} \delta \left(\min \left(\frac{M(f\alpha, Q\alpha, h\alpha, t)}{M(f\alpha, g\alpha, h\alpha, t)}, \frac{M(P\alpha, Q\alpha, h\alpha, t)}{M(P\alpha, g\alpha, h\alpha, t)} \right) \right) \xi(t) dt$$

$$\int_0^{\left\{ \varphi \left(\min \left(\frac{M(\alpha, \alpha, R\alpha, t), M(\alpha, \alpha, \alpha, t)}{M(\alpha, \alpha, R\alpha, t), M(R\alpha, R\alpha, \alpha, t)}, \frac{M(\alpha, \alpha, R\alpha, t), M(\alpha, \alpha, R\alpha, t)}{M(\alpha, \alpha, R\alpha, t), M(\alpha, \alpha, R\alpha, t)} \right) \right) \right\}} \delta \left(\min \left(\frac{M(\alpha, \alpha, R\alpha, t)}{M(\alpha, \alpha, R\alpha, t)}, \frac{M(\alpha, \alpha, R\alpha, t)}{M(\alpha, \alpha, R\alpha, t)} \right) \right) \xi(t) dt$$

$$\int_0^{M(\alpha, \alpha, R\alpha, \vartheta(t))} \xi(t) dt \geq \int_0^{\left\{ \varphi(M(\alpha, \alpha, R\alpha, t)) \right\}} \delta(1) \xi(t) dt \geq \int_0^{\{M(\alpha, \alpha, R\alpha, t)\}} \xi(t) dt$$

$$i. e \int_0^{M(\alpha, \alpha, R\alpha, \vartheta(t))} \xi(t) dt \geq \int_0^{\{M(\alpha, \alpha, R\alpha, t)\}} \xi(t) dt$$

From remark (2.1), So that $R\alpha = \alpha$ and hence $R = \alpha$.

Thus $P\alpha = Q\alpha = R\alpha = f\alpha = g\alpha = h\alpha = \alpha$

Suppose that $\beta \neq \alpha$ is a common fixed point of P, Q, R, f, g and h .

$$\int_0^{M(\beta, \alpha, R\alpha, \vartheta(t))} \xi(t) dt \geq \int_0^{M(P\beta, Q\alpha, R\alpha, \vartheta(t))} \xi(t) dt$$

$$\int_0^{\left\{ \varphi \left(\min \left(\begin{matrix} M(f\beta, g\alpha, h\alpha, t), M(f\beta, P\beta, Q\alpha, t), \\ M(g\alpha, Q\alpha, R\alpha, t), M(h\alpha, R\alpha, P\beta, t), \\ M(f\beta, g\alpha, R\alpha, t), M(P\beta, g\alpha, h\alpha, t) \end{matrix} \right) \right) \right\}} \xi(t) dt$$

$$+ \int_0^{\left\{ \delta \left(\min \left(\frac{M(f\beta, Q\alpha, h\alpha, t)}{M(f\beta, g\alpha, h\alpha, t)}, \frac{M(P\beta, Q\alpha, h\alpha, t)}{M(P\beta, g\alpha, h\alpha, t)} \right) \right) \right\}} \xi(t) dt$$

$$\int_0^{\left\{ \varphi \left(\min \left(\begin{matrix} M(\beta, \alpha, \alpha, t), M(\beta, \beta, \alpha, t), \\ M(\alpha, \alpha, \alpha, t), M(\alpha, \alpha, \beta, t), \\ M(\beta, \alpha, \alpha, t), M(\beta, \alpha, \alpha, t) \end{matrix} \right) \right) \right\}} \xi(t) dt$$

$$+ \int_0^{\left\{ \delta \left(\min \left(\frac{M(\beta, \alpha, \alpha, t)}{M(\beta, \alpha, \alpha, t)}, \frac{M(\beta, \alpha, \alpha, t)}{M(\beta, \alpha, \alpha, t)} \right) \right) \right\}} \xi(t) dt$$

$$\int_0^{M(\beta, \alpha, \alpha, \phi(t))} \xi(t) dt \geq \int_0^{\left\{ \varphi \left(\frac{M(\beta, \alpha, \alpha, t)}{\delta(1)} \right) \right\}} \xi(t) dt \geq \int_0^{M(\beta, \alpha, \alpha, t)} \xi(t) dt$$

$$i.e \int_0^{M(\beta, \alpha, \alpha, \phi(t))} \xi(t) dt \geq \int_0^{M(\beta, \alpha, \alpha, t)} \xi(t) dt$$

From Remark (2.1)

So that $\phi = \psi$. Thus ψ is the unique common fixed point of P, Q, R, f, g and h .

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